

## ON SUNS, MOONS AND BEST APPROXIMATION IN M-SPACES

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ABSTRACT. A metric space  $(X, d)$  in which for every  $x, y \in X$  and for every  $t, 0 \leq t \leq 1$  there exists exactly one point  $z \in X$  such that  $d(x, z) = (1 - t)d(x, y)$  and  $d(z, y) = td(x, y)$  is called an M-space. In this paper we discuss suns and moons in M-spaces and characterize these via best approximation thereby extending corresponding known results in normed linear spaces to M-spaces.

**Introduction** The concept of a sun in Approximation Theory was first introduced in normed linear spaces by Klee [5] but the terminology 'sun' was proposed by Effimov and Steckin [3]. We recall that a set  $V$  is a sun iff whenever  $v_0 \in V$  is a best approximation to some element  $x \notin V$  then  $v_0$  is a best approximation to every element on the ray from  $v_0$  through  $x$ . Since every convex set in a normed linear space has this property, a sun may be regarded as a generalization of a convex set. Vlasov [10], who developed the concept further, showed that in a smooth Banach space every proximal sun is convex. In view of Vlasov's result, the most famous unsolved problem in Approximation Theory viz. whether or not every Chebyshev set in a Hilbert space is convex, may be stated equivalently as "Is every Chebyshev set in a Hilbert space a sun?" The concept of a moon, which is a generalization of sun, was introduced by Amir and Deutsch [1] and their special interest was in determining those normed linear spaces in which every moon is a sun. Knowing such spaces is quite useful as it is much easier to verify that a given set is a moon than verify it is a sun.

Our purpose in this paper is to discuss these concepts in M-spaces [4] (also called strongly convex spaces [9]) and extend some of the results proved in [1] and [6] to M-spaces.

To start with, we give a few notations and recall a few definitions.

Let  $(X, d)$  be a metric space and  $x, y, z \in X$ . We say that  $z$  is between  $x$  and  $y$  if  $d(x, z) + d(z, y) = d(x, y)$ . For any two points  $x, y$  of  $X$ , the set  $\{z \in X : d(x, z) + d(z, y) = d(x, y)\}$  is called the metric segment and is denoted by  $G[x, y]$ .

A metric space  $(X, d)$  is said to be convex [9] if for every  $x, y \in X$  and for every  $t, 0 \leq t \leq 1$  there exists at least one point  $z \in X$  such that

$$d(x, z) = (1 - t)d(x, y) \text{ and } d(z, y) = td(x, y)$$

The space  $(X, d)$  is said to be strongly convex [9] or an M-space [4] if such a  $z$  exists and is unique for each pair  $x, y$  of  $X$ .

Thus for strongly convex metric spaces each  $t, 0 \leq t \leq 1$ , determines a unique point of the segment  $G[x, y]$ .

Let  $G(x, y, -)$  denote the largest line segment containing  $G[x, y]$  for which  $x$  is an extreme point i.e. the ray starting from  $x$  and passing through  $y$ ,  $G_1(x, y, -)$  denotes  $G(x, y, -) \setminus G[x, y]$  and  $K(v_0, x) \equiv \bigcup B(z, d(z, v_0))$ ,  $z \in G_1(v_0, x, -)$  where  $B(z, r)$  stands for an open ball with centre  $z$  and radius  $r$ .

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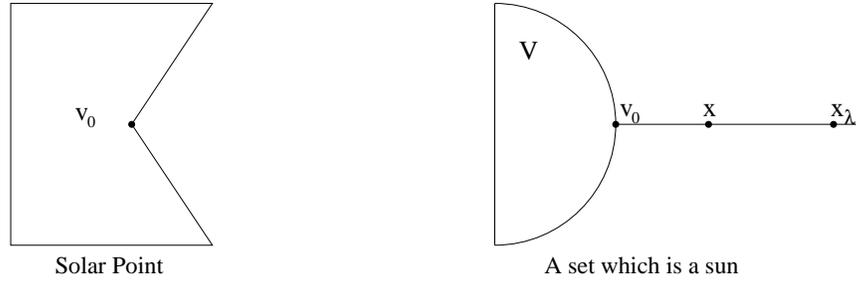


Figure 1: A non sun set and a set which is a sun

A subset  $V$  of an M-space  $(X, d)$  is said to be a cone with vertex  $v_0$  if  $G(v_0, y, -) \subseteq V$  whenever  $y \in V$ .

Let  $V$  be a non-empty subset of a metric space  $(X, d)$  and  $x \in X$ . An element  $v_0 \in V$  is called a best approximation to  $x$  if  $d(x, v_0) = dist(x, V)$ . We denote by  $P_V(x)$ , the set of all best approximants to  $x$  in  $V$ . The set  $V$  is said to be proximal if  $P_V(x) \neq \emptyset$  for each  $x \in X$  and is said to be Chebyshev if  $P_V(x)$  is exactly singleton for each  $x \in X$ .

For  $v_0 \in V$ ,  $P_V^{-1}(v_0) = \{x \in X : v_0 \in P_V(x)\}$ . It is easy to prove (see [8]) that if  $x \in P_V^{-1}(v_0)$  then  $x_\lambda \in P_V^{-1}(v_0)$  for every  $x_\lambda \in G[v_0, x]$  i.e.  $v_0 \in P_V(x_\lambda)$ . On the other hand,  $v_0$  may not be in  $P_V(x_\lambda)$  for  $x_\lambda \in G_1(v_0, x, -)$ . This motivates the following definition introduced in normed linear spaces by Effimov and Steckin [3]: If  $V$  is a proximal subset of an M-space  $(X, d)$ , a point  $v_0 \in V$  is called a solar point ( see Fig. 1 left diagram) of  $V$  if  $x \in P_V^{-1}(v_0)$  implies  $x_\lambda \in P_V^{-1}(v_0)$  for every  $x_\lambda \in G_1(v_0, x, -)$ . The set  $V$  is called a sun (see Fig. 1 right diagram) if for each  $x \in X \setminus V$ , every  $v_0 \in P_V(x)$  is a solar point of  $V$  i.e. for all  $v_0 \in P_V(x)$ ,  $v_0 \in P_V(z)$  for all  $z \in G_1(v_0, x, -)$ .

Let  $V$  be a subset of an M-space  $(X, d)$ . A point  $v_0 \in V$  is called a lunar point if  $x \in X$  and  $K(v_0, x) \cap V \neq \emptyset$  imply  $v_0 \in \overline{K(v_0, x) \cap V}$ . The set  $V$  is called a moon if each of its point is lunar.

The set  $V = \{(x, y) \in R^2 : x^2 + 4y^2 \geq 1\}$  in Euclidean 2-space  $R^2$  is a moon (see [2], p.38). We shall see that each sun in an M-space is a moon. However, the converse is not true (see [1]).

For proximal subsets of an M-space, we have:

**Theorem 1** *A proximal subset  $V$  of an M-space  $(X, d)$  is a sun if and only if for any  $v_0 \in V$ , the set  $P_V^{-1}(v_0)$  is a cone with vertex  $v_0$ .*

**Proof** Suppose  $V$  is a sun and  $x \in P_V^{-1}(v_0)$  i.e.  $v_0 \in P_V(x)$ . We want to show that  $G(v_0, x, -) \subseteq P_V^{-1}(v_0)$ . Since  $v_0 \in P_V(x)$  and  $V$  is a sun,  $v_0 \in P_V(z)$  for all  $z \in G_1(v_0, x, -)$  and consequently for all  $z \in G(v_0, x, -)$  i.e.  $z \in P_V^{-1}(v_0)$  for all  $z \in G(v_0, x, -)$  i.e.  $P_V^{-1}(v_0)$  is a cone with vertex  $v_0$ .

Conversely, let  $x \in X \setminus V$  and  $y \in P_V(x)$  i.e.  $x \in P_V^{-1}(y)$  where  $y \in V$ . Since  $P_V^{-1}(y)$  is a cone with vertex  $y$ ,  $G(y, x, -) \subseteq P_V^{-1}(y)$  i.e.  $y \in P_V(z)$  for all  $z \in G(y, x, -)$ . Hence  $V$  is a sun.

**Theorem 2** *A proximal subset  $V$  of an M-space  $(X, d)$  is a sun if and only if for any  $v_0 \in V$  and  $x \in P_V^{-1}(v_0)$ ,  $K(v_0, x) \cap V = \emptyset$ .*

**Proof** Suppose  $V$  is a sun. Let  $v_0 \in V$  and  $x \in P_V^{-1}(v_0)$ . Since  $v_0 \in P_V(x)$  and  $V$  is a sun,  $v_0 \in P_V(z)$  for all  $z \in G(v_0, x, -)$ . To show  $K(v_0, x) \cap V = \emptyset$ . Suppose  $u \in K(v_0, x) \cap V$

i.e.  $u \in B(z, d(z, v_0))$  for some  $z \in G_1(v_0, x, -)$  i.e.  $d(z, u) \leq d(z, v_0)$  and so  $v_0 \notin P_V(z)$  as  $u \in V$ , a contradiction. Therefore  $K(v_0, x) \cap V = \emptyset$ .

For the converse part, suppose  $V$  is not a sun. Then there exists  $x \in X \setminus V$  and  $v_0 \in P_V(x)$  such that  $v_0 \notin P_V(z)$  for some  $z \in G(v_0, x, -)$ . Then  $d(z, v_1) \leq d(z, v_0)$  where  $v_1 \in P_V(z)$  i.e.  $v_1 \in B(z, d(z, v_0))$  for some  $z \in G(v_0, x, -)$ . i.e  $v_1 \in K(v_0, x)$ . Also  $v_1 \in V$  and therefore  $K(v_0, x) \cap V \neq \emptyset$ , a contradiction. Hence  $V$  is a sun.

**Note** In normed linear spaces, Theorem 2 was proved by Amir and Deutsch [1] (see also [6], p. 467).

**Lemma 3**  $K(v_0, x) = K(v_0, y)$  for all  $y \in G[v_0, x]$ , where  $x \in X, V \subset X$  and  $v_0 \in P_V(x)$ .

**Proof**  $K(v_0, x) \equiv \bigcup B(z_1, d(z_1, v_0)), z_1 \in G_1(v_0, x, -), K(v_0, y) \equiv \bigcup B(z_2, d(z_2, v_0)), z_2 \in G_1(v_0, y, -)$ .

Let  $z \in K(v_0, x)$  then  $z \in B(z_1, d(z_1, v_0))$  for at least one  $z_1 \in G_1(v_0, x, -)$ . Now any  $z_1 \in G_1(v_0, x, -)$  is also a point on  $G_1(v_0, y, -)$  i.e.  $z_1 = z_2$  for some  $z_2 \in G_1(v_0, y, -)$  i.e.  $z \in \bigcup B(z_2, d(z_2, v_0)), z_2 \in G_1(v_0, y, -)$ . Therefore,

$$(1) \quad K(v_0, x) \subseteq K(v_0, y)$$

Let  $z \in K(v_0, y)$  i.e  $z \in B(z_2, d(z_2, v_0))$  for at least one  $z_2 \in G_1(v_0, y, -)$ . If  $z_2 \in G_1(v_0, x, -)$  then  $z \in K(v_0, x)$  and so  $K(v_0, y) \subseteq K(v_0, x)$ . If  $z_2 \in G[y, x]$ , consider  $z't \in G_1(v_0, x, -)$ . Then

$$\begin{aligned} d(z, z't) &\leq d(z, z_2) + d(z_2, z't) \\ &\leq d(z_2, v_0) + d(z_2, z't) \\ &= d(z't, v_0). \end{aligned}$$

Therefore  $z \in B(z't, d(z't, v_0))$  and so  $z \in K(v_0, x)$ . Consequently

$$(2) \quad K(v_0, y) \subseteq K(v_0, x).$$

(1) and (2) imply  $K(v_0, x) = K(v_0, y)$ .

The following theorem shows that we may assume in the definition of lunar point that  $x$  has  $v_0$  as a best approximation from  $V$ .

**Theorem 4** Let  $V$  be a subset of an  $M$ -space  $(X, d)$  and  $v_0 \in V$ . Then the following are equivalent:

- (i)  $v_0$  is a lunar point
- (ii) whenever  $v_0$  is a best approximation to  $x$  with  $K(v_0, x) \cap V \neq \emptyset$  then  $v_0 \in \overline{K(v_0, x) \cap V}$ .

**Proof** (i)  $\Rightarrow$  (ii) is trivial. (ii)  $\Rightarrow$  (i). Let  $x \in X$  and  $K(v_0, x) \cap V \neq \emptyset$ . To show  $v_0 \in \overline{K(v_0, x) \cap V}$ . If  $v_0$  is a best approximation to  $x$  then by (ii),  $v_0 \in \overline{K(v_0, x) \cap V}$ . If  $v_0$  is not a best approximation to  $x$  then two cases arise:

- (a)  $v_0$  is not a local best approximation to  $x$ ,
- (b)  $v_0$  is a local best approximation to  $x$ .

Case (a): If  $v_0$  is not a local best approximation to  $x$  i.e. for all  $\epsilon \geq 0$  there exists  $v_\epsilon \in V$  such that  $d(v_\epsilon, v_0) \leq \epsilon$  and  $d(v_\epsilon, x) \leq d(v_0, x)$ . Then  $v_\epsilon \in B(x, d(v_0, x)) \subset K(v_0, x)$ . Therefore every neighbourhood of  $v_0$  contains an element  $v_\epsilon$  of  $K(v_0, x) \cap V$  other than  $v_0$  i.e.  $v_0$  is a limit point of  $K(v_0, x) \cap V$  and so  $v_0 \in \overline{K(v_0, x) \cap V}$ . Hence  $v_0$  is a lunar point.

Case (b): If  $v_0$  is a local best approximation to  $x$  i.e.  $v_0$  is a best approximation to  $x$  from  $V \cap B(v_0, \epsilon)$  for some  $\epsilon \geq 0$ . Let  $z \in G[v_0, x]$  such that  $d(z, v_0) \leq \frac{\epsilon}{2}$  then by Lemma 3  $K(v_0, z) = K(v_0, x)$  and  $v_0$  is a best approximation to  $z$  from  $V$  [7]. So (ii) implies  $v_0 \in \overline{K(v_0, z) \cap V} = \overline{K(v_0, x) \cap V}$  and therefore  $v_0$  is a lunar point.

**Remark** For normed linear spaces, above theorem was proved by Amir and Deutsch [1]-Lemma 2.7.

**Corollary 5** *Every sun in an  $M$ -space is a moon.*

**Proof** Let  $V$  be a sun. Suppose  $V$  is not a moon i.e. there exists  $v_0 \in V$  which is not a lunar point i.e.  $v_0$  is a best approximation to  $x \in X$  with  $K(v_0, x) \cap V \neq \emptyset$  but  $v_0 \notin \overline{K(v_0, x) \cap V}$ .

As  $V$  is a sun, Theorem 2 implies  $K(v_0, x) \cap V = \emptyset$  whenever  $v_0$  is a best approximation to  $x \in X$ .

Since these two statements are contradictory, the result follows.

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