Deformations of finite hypergroups

SATOSHI KAWAKAMI, TATSUYA TSURII AND SATOE YAMANAKA Received 14 November 2014

ABSTRACT. The purpose of the present paper is to introduce q-deformations of finite groups of low order, for examples, cyclic groups, symmetric groups, dihedral groups and the quaternion group in the category of hypergroups. Moreover we discuss qdeformations of certain finite hypergroups.

1 Introduction

We investigate q-deformations of finite groups and finite hypergroups in the category of hypergroups. It is known that there is no q-deformations of finite groups in the category of quantum groups ([24]). However we introduce that there are many q-deformations of finite groups in the category of hypergroups.

Hypergroups $\mathbb{Z}_q(2)$ of order two with a parameter q ($0 < q \leq 1$) are interpreted as q-deformations of the cyclic group \mathbb{Z}_2 . This fact is our motivation that we started to investigate q-deformations of finite groups and finite hypergroups.

In section 3, we discuss q-deformations of the cyclic group \mathbb{Z}_3 of order three and the cyclic group \mathbb{Z}_4 of order four. In section 4, we discuss q-deformations of the symmetric group S_3 , the dihedral group D_4 and quaternion group Q_4 . These q-deformations are obtained by applying a notion of a semi-direct product hypergroup introduced by H. Heyer and S. Kawakami (see [5]).

Moreover we study q-deformations of certain finite hypergroups of low order, the orbital hypergroups $\mathcal{K}^{\alpha}(\mathbb{Z}_3)$ of \mathbb{Z}_3 and $\mathcal{K}^{\alpha}(\mathbb{Z}_4)$ of \mathbb{Z}_4 , the character hypergroups $\mathcal{K}(\widehat{S}_3)$ of S_3 , $\mathcal{K}(\widehat{D}_4)$ of D_4 and $\mathcal{K}(\widehat{Q}_4)$ of Q_4 , the conjugacy class hypergroups $\mathcal{K}(S_3)$ of S_3 , $\mathcal{K}(D_4)$ of D_4 and $\mathcal{K}(Q_4)$ of Q_4 in section 5.

2 Preliminaries

For a finite set $K = \{c_0, c_1, \dots, c_n\}$, we denote by $M^b(K)$ and $M^1(K)$, the set of all complex valued measures on K and the set of all non-negative probability measures on K respectively, namely

$$M^{b}(K) := \left\{ \sum_{j=0}^{n} a_{j} \delta_{c_{j}} : a_{j} \in \mathbb{C} \ (j = 0, 1, 2, \cdots, n) \right\},$$
$$M^{1}(K) := \left\{ \sum_{j=0}^{n} a_{j} \delta_{c_{j}} : a_{j} \ge 0 \ (j = 0, 1, 2, \cdots, n), \ \sum_{j=0}^{n} a_{j} = 1 \right\}$$

where the symbol δ_c stands for the Dirac measure in $c \in K$. For $\mu = a_0 \delta_{c_0} + a_1 \delta_{c_1} + \cdots + a_n \delta_{c_n} \in M^b(K)$, the support of μ is

$$\operatorname{supp}(\mu) := \{ c_j \in K : a_j \neq 0 \ (j = 0, 1, 2, \cdots, n) \}.$$

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Axiom A finite hypergroup $K = (K, M^b(K), \circ, *)$ consists of a finite set $K = \{c_0, c_1, \cdots, c_n\}$ together with an associative product (called convolution) \circ and an involution * in $M^b(K)$ satisfying the following conditions.

- (1) The space $(M^b(K), \circ, *)$ is an associative *-algebra with unit δ_{c_0} .
- (2) For $c_i, c_j \in K$, the convolution $\delta_{c_i} \circ \delta_{c_j}$ belongs to $M^1(K)$.
- (3) There exists an involutive bijection $c_i \mapsto c_i^*$ on K such that $\delta_{c_i^*} = \delta_{c_i}^*$. Moreover $c_j = c_i^*$ if and only if $c_0 \in \text{supp}(\delta_{c_i} \circ \delta_{c_j})$ for all $c_i, c_j \in K$.

A finite hypergroup K is called *commutative* if the convolution \circ on $M^b(K)$ is commutative.

Let K and L be finite hypergroups. A mapping $\varphi : K \to L$ is called a (hypergroup) homomorphism of K into L if there exists a *-homomorphism $\tilde{\varphi}$ of $M^b(K)$ into $M^b(L)$ as *-algebras such that $\delta_{\varphi(c)} = \tilde{\varphi}(\delta_c)$. If $\tilde{\varphi}$ is bijective, φ is called an *isomorphism* of K onto L. In the case that L = K, an isomorphism $\varphi : K \to K$ is called an *automorphism* of K. The set of all automorphisms of K becomes a group and it is denoted by $\operatorname{Aut}(K)$. Let G be a finite group. A homomorphism $\alpha : G \to \operatorname{Aut}(K)$ is called an action of G on K.

For a commutative hypergroup K, a complex-valued function χ on K is called a *character* if χ is linearly extendable on $M^b(K)$ to be $\tilde{\chi}(\delta_{c_i}) = \chi(c_i)$ and satisfying that $\tilde{\chi}(\delta_{c_0}) = 1$, $\tilde{\chi}(\delta_{c_i} \circ \delta_{c_j}) = \tilde{\chi}(\delta_{c_i})\tilde{\chi}(\delta_{c_j})$ and $\tilde{\chi}(\delta_{c_i}^*) = \overline{\tilde{\chi}(\delta_{c_i})}$ for all $c_i, c_j \in K$. We denote the trivial character by χ_0 . Let \hat{K} be the set of all characters of K. A convolution on \hat{K} is defined by multiplication of functions on K. Then \hat{K} becomes a signed hypergroup and the duality $\hat{K} \cong K$ holds.

Conjugacy class hypergroup Let G be a finite group. For $g \in G$, put $\alpha_g(k) = Ad_g(k) = gkg^{-1}$ ($k \in G$). Then α is an action of G on G. Hence we obtain the orbital hypergroup $\mathcal{K}^{\alpha}(G)$ which we denote by $\mathcal{K}(G)$ which is called a conjugacy class hypergroup of G.

Character hypergroup For a finite group G, $\hat{G} = \{\pi_0, \pi_1, \dots, \pi_m\}$ is the set of the all equivalence classes of irreducible representations of G. For $\pi_j \in \hat{G}$, a character χ_j associated with π_j is defined by

$$\chi_j(g) = \frac{1}{\dim \pi_j} \operatorname{tr}(\pi_j(g)).$$

Then $\mathcal{K}(\hat{G}) = \{\chi_0, \chi_1, \cdots, \chi_m\}$ becomes a commutative hypergroup with unit χ_0 by the multiplication of functions on G.

Hypergroup join For two finite hypergroups $H = \{h_0, h_1, \dots, h_m\}$ and $L = \{\ell_0, \ell_1, \dots, \ell_k\}$, a hypergroup join

$$H \lor L = \{h_0, h_1, \cdots, h_m, \ell_1, \cdots, \ell_k\}$$

is defined by the convolution \diamond whose structure equations are

$$\delta_{h_i} \diamond \delta_{h_j} = \delta_{h_i} \circ \delta_{h_j}, \quad \delta_{h_i} \diamond \delta_{\ell_j} = \delta_{\ell_j}$$
$$\delta_{\ell_i} \diamond \delta_{\ell_j} = \delta_{\ell_i} \circ \delta_{\ell_j} \text{ when } \ell_j \neq \ell_i^*,$$
$$\delta_{\ell_i} \diamond \delta_{\ell_i}^* = n_i^0 \omega(H) + \sum_{j=1}^k n_i^j \delta_{\ell_j}$$

where $\delta_{\ell_i} \circ \delta^*_{\ell_i} = n_i^0 \delta_{\ell_0} + \sum_{j=1}^k n_i^j \delta_{\ell_j}$ and $\omega(H)$ is the normalized Haar measure of H.

3 Deformations of finite abelian groups

Let $K = \{c_0, c_1\}$ be a hypergroup of order two. Then the structure of K is determined by

$$\delta_{c_1} \circ \delta_{c_1} = q\delta_{c_0} + (1-q)\delta_{c_1}$$

where $0 < q \leq 1$. We denote it by $\mathbb{Z}_q(2)$ which is interpreted as a q-deformation of \mathbb{Z}_2 . Stimulating by this fact, we have started to study q-deformations of finite groups.

3.1 Deformation $\mathbb{Z}_q(3)$ of \mathbb{Z}_3

First of all we discuss a q-deformation of \mathbb{Z}_3 . It is easy to check the following proposition directly and this fact is also described in the paper ([19], [23] and [25]).

Proposition 3.1 Let $K = \{c_0, c_1, c_2\}$ be a hypergroup of order three. For each q (0 < $q \leq 1$) there exists a unique hypergroup of order three such that $\delta_{c_1}^* = \delta_{c_2}$ and $\delta_{c_1} \circ \delta_{c_2} = q\delta_{c_0} + a_1\delta_{c_1} + a_2\delta_{c_2}$.

We denote the above K by $\mathbb{Z}_q(3)$, which is interpreted as a q-deformation of \mathbb{Z}_3 . The structure equations of $\mathbb{Z}_q(3) = \{c_0, c_1, c_2\} \ (0 < q \leq 1)$ are determined by

$$\begin{split} \delta_{c_1} \circ \delta_{c_2} &= q \delta_{c_0} + \frac{1-q}{2} \delta_{c_1} + \frac{1-q}{2} \delta_{c_2}, \\ \delta_{c_1} \circ \delta_{c_1} &= \frac{1-q}{2} \delta_{c_1} + \frac{1+q}{2} \delta_{c_2}, \\ \delta_{c_2} \circ \delta_{c_2} &= \frac{1+q}{2} \delta_{c_1} + \frac{1-q}{2} \delta_{c_2}. \end{split}$$

Put $\widehat{\mathbb{Z}_q(3)} = \{\chi_0, \chi_1, \chi_2\}$. Then the character table of $\mathbb{Z}_q(3)$ is

	c_0	c_1	c_2
χ_0	1	1	1
χ_1	1	ω_q	$\overline{\omega_q}$
χ_2	1	$\overline{\omega_q}$	ω_q

where $\omega_q = \frac{-q+i\sqrt{q^2+2q}}{2}$.

By the symmetry of the character table we see that $\widehat{\mathbb{Z}}_q(3) \cong \mathbb{Z}_q(3)$.

3.2 Deformation $\mathbb{Z}_{(p,q)}(4)$ of \mathbb{Z}_4

We investigated several kinds of extension problem in the category of commutative hypergroups, refer to [6], [8], [10], [11], [12], [13], [14], [15], [16], [17], [18]. The cyclic group \mathbb{Z}_4 of order four is a non-splitting extension of \mathbb{Z}_2 by \mathbb{Z}_2 . Then one can consider a non-splitting extension $\mathbb{Z}_{(p,q)}(4)$ ($0 , <math>0 < q \le 1$) of $\mathbb{Z}_q(2)$ by $\mathbb{Z}_p(2)$ as follows.

Proposition 3.2 (Example 4.2 in [14]) For (p,q) $(0 there exists a unique hypergroup <math>\mathbb{Z}_{(p,q)}(4) = \{c_0, c_1, c_2, c_3\}$ of order four, which is an extension hypergroup of $\mathbb{Z}_q(2)$ by $\mathbb{Z}_p(2) = \{c_0, c_2\}$ such that $c_1^* = c_3$.

The structure of $\mathbb{Z}_{(p,q)}(4) = \{c_0, c_1, c_2, c_3\} \ (0 is given by$

$$\begin{split} \delta_{c_1} \circ \delta_{c_1} &= \delta_{c_3} \circ \delta_{c_3} = \frac{1-q}{2} \delta_{c_1} + q \delta_{c_2} + \frac{1-q}{2} \delta_{c_3}, \\ \delta_{c_2} \circ \delta_{c_2} &= p \delta_{c_0} + (1-p) \delta_{c_2}, \quad \delta_{c_1} \circ \delta_{c_2} = \frac{1-p}{2} \delta_{c_1} + \frac{1+p}{2} \delta_{c_3}, \\ \delta_{c_1} \circ \delta_{c_3} &= \frac{2pq}{1+p} \delta_{c_0} + \frac{1-q}{2} \delta_{c_1} + \frac{q-pq}{1+p} \delta_{c_2} + \frac{1-q}{2} \delta_{c_3}, \\ \delta_{c_2} \circ \delta_{c_3} &= \frac{1+p}{2} \delta_{c_1} + \frac{1-p}{2} \delta_{c_3}. \end{split}$$

Put $\widehat{\mathbb{Z}_{(p,q)}(4)} = \{\chi_0, \chi_1, \chi_2, \chi_3\}$. Then the character table of $\mathbb{Z}_{(p,q)}(4)$ is

	c_0	c_1	c_2	c_3	
χ_0	1	1	1	1	
χ_1	1	$i\sqrt{pq}$	-p	$-i\sqrt{pq}$	
χ_2	1	-q	1	-q	
χ_3	1	$-i\sqrt{pq}$	-p	$i\sqrt{pq}$	

It is easy to see that $\mathbb{Z}_{(p,q)}(4)$ is interpreted as a (p,q)-deformation of \mathbb{Z}_4 and $\mathbb{Z}_{(p,q)}(4) \cong$ $\mathbb{Z}_{(q,p)}(4).$

4 Deformations of non-abelian finite groups

Let α be an action of a finite group G on a finite hypergroup $H = (H, M^b(H), \circ, *)$. Then a semi-direct product hypergroup $S := H \rtimes_{\alpha} G$ is introduced in [5]. A convolution \circ_{α} in $M^b(S)$ is defined by

$$(\varepsilon_{h_1} \otimes \delta_{g_1}) \circ_{\alpha} (\varepsilon_{h_2} \otimes \delta_{g_2}) := (\varepsilon_{h_1} \circ \varepsilon_{\alpha_{g_1}(h_2)} \otimes \delta_{g_1g_2}),$$

where ε and δ stand for Dirac measures in $M^b(H)$ and $M^b(G)$ respectively. Unit element is $\varepsilon_e \otimes \delta_e$. An involution – is

$$(\mu \otimes \delta_g)^- := \alpha_g^{-1}(\mu^*) \otimes \delta_{g^{-1}}$$

for all $\mu \in M^b(H)$ and $q \in G$.

4.1 Deformation $S_q(3)$ of the symmetric group S_3 The symmetric group S_3 is a semi-direct product $\mathbb{Z}_3 \rtimes_{\alpha} \mathbb{Z}_2$ where α is an action of \mathbb{Z}_2 on \mathbb{Z}_3 .

Let α be an action of $\mathbb{Z}_2 = \{e, g\}$ on a hypergroup $\mathbb{Z}_q(3) = \{h_0, h_1, h_2\}$ $(0 < q \leq 1)$ such that

$$\alpha_g(h_1) = h_2, \ \ \alpha_g(h_2) = h_1.$$

Then we obtain a semi-direct product hypergroup

$$S_q(3) := \mathbb{Z}_q(3) \rtimes_\alpha \mathbb{Z}_2$$

which is a q-deformation of the symmetric group $S_3 = \mathbb{Z}_3 \rtimes_{\alpha} \mathbb{Z}_2$.

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4.2 Deformation $D_{(p,q)}(4)$ of the dihedral group D_4

The dihedral group D_4 is written by a semi-direct product $\mathbb{Z}_4 \rtimes_{\alpha} \mathbb{Z}_2$.

Let $H = \mathbb{Z}_{(p,q)}(4) = \{h_0, h_1, h_2, h_3\}$ (0 be the <math>(p,q)-deformation of \mathbb{Z}_4 and α an action of $\mathbb{Z}_2 = \{e, g\}$ on $\mathbb{Z}_{(p,q)}(4)$ given by

 $\alpha_g(h_1) = h_3, \ \alpha_g(h_2) = h_2, \ \alpha_g(h_3) = h_1.$

Then we obtain a semi-direct product hypergroup

$$D_{(p,q)}(4) := \mathbb{Z}_{(p,q)}(4) \rtimes_{\alpha} \mathbb{Z}_{2}.$$

Hence, we obtain a (p,q)-deformation $D_{(p,q)}(4)$ of the dihedral group D_4 .

4.3 Another deformation $W_q(4)$ of the dihedral group D_4

The dihedral group D_4 is also written by a semi-direct product $(\mathbb{Z}_2 \times \mathbb{Z}_2) \rtimes_{\beta} \mathbb{Z}_2$ where β is a flip action of \mathbb{Z}_2 on $\mathbb{Z}_2 \times \mathbb{Z}_2$.

Let $\mathbb{Z}_q(2) \times \mathbb{Z}_q(2) = \{(h_0, h_0), (h_0, h_1), (h_1, h_0), (h_1, h_1); h_0, h_1 \in \mathbb{Z}_q(2)\}$ be a q-deformat-

ion of $\mathbb{Z}_2 \times \mathbb{Z}_2$. Let β be a flip action of $\mathbb{Z}_2 = \{e, g\}$ on $\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)$ given by

 $\beta_g((h_i, h_j)) = (h_j, h_i) \quad (i, j = 0 \text{ or } 1).$

Then we obtain a semi-direct product hypergroup

$$W_q(4) := (\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)) \rtimes_\beta \mathbb{Z}_2.$$

The hypergroup $W_q(4)$ is another q-deformation of D_4 .

4.4 Deformation $Q_q(4)$ of the quaternion group Q_4

The structure of the quaternion group $Q_4 = \{\pm 1, \pm i, \pm j, \pm k\}$ is determined by

$$k^2 = j^2 = k^2 = -1, \quad ij = k.$$

Let α be an action of $\mathbb{Z}_2 = \{e, g\}$ on $\mathbb{Z}_4 = \{h_0, h_1, h_2, h_3\}$ such that

$$\alpha_g(h_1) = h_3, \ \ \alpha_g(h_2) = h_2, \ \ \alpha_g(h_3) = h_1.$$

Let c be a \mathbb{Z}_4 -valued 2-cocycle of \mathbb{Z}_2 which is also given by

$$c(e, e) = c(e, g) = c(g, e) = h_0$$
 and $c(g, g) = h_2$.

Then a twisted semi-direct product group $\mathbb{Z}_4 \rtimes^c_{\alpha} \mathbb{Z}_2$ is defined by the product

$$(h,g)(h',g') = (h\alpha_q(h')c(g,g'),gg')$$

for $h, h' \in \mathbb{Z}_4$ and $g, g' \in \mathbb{Z}_2$. The quaternion group Q_4 is isomorphic to $\mathbb{Z}_4 \rtimes_{\alpha}^c \mathbb{Z}_2$. Hence we interpret Q_4 as a twisted semi-direct product group $\mathbb{Z}_4 \rtimes_{\alpha}^c \mathbb{Z}_2$.

Let $\mathbb{Z}_{(1,q)}(4) = \{h_0, h_1, h_2, h_3\}$ be a q-deformation of \mathbb{Z}_4 with a subgroup $\{h_0, h_2\}$ and c a $\mathbb{Z}_{(1,q)}(4)$ -valued 2-cocycle which is also given by

$$c(e, e) = c(e, g) = c(g, e) = h_0$$
 and $c(g, g) = h_2$.

Then, we obtain a twisted semi-direct product hypergroup

$$Q_q(4) := \mathbb{Z}_{(1,q)}(4) \rtimes_{\alpha}^c \mathbb{Z}_2$$

The hypergroup $Q_q(4)$ is a q-deformation of the quaternion group $Q_4 = \mathbb{Z}_4 \rtimes_{\alpha}^c \mathbb{Z}_2$.

5 Deformations of finite hypergroups

In this section we discuss q-deformations of several kinds of finite hypergroups in a similar way to the case of finite groups.

5.1 Deformations of orbital hypergroups

Given an action α of a finite group G on a commutative hypergroup H, we obtain a orbit $O = \{\alpha_g(h) ; g \in G\}$ of $h \in H$ under the action α . Let $\{O_0, O_1, \dots, O_m\}$ be the set of all orbits in H. We denote an element c_j which is corresponding to each orbit O_j and put $H^{\alpha} = \{c_0, c_1, \dots, c_m\}$. Let $M^b(H)^{\alpha}$ denote the fixed point algebra of $M^b(H)$ under the action α , namely

$$M^{b}(H)^{\alpha} = \{ \mu \in M^{b}(H) ; \alpha_{q}(\mu) = \mu \text{ for all } g \in G \}.$$

We note that $M^b(H)^{\alpha}$ is a *-subalgebra of $M^b(H)$. For $c_i \in H^{\alpha}$, put

$$\delta_{c_j} = \frac{1}{|O_j|} \sum_{h \in O_j} \delta_h = \frac{1}{|G|} \sum_{g \in G} \alpha_g(\delta_h).$$

Then $\delta_{c_j} \in M^b(H)^{\alpha} \cap M^1(H)$. $\mathcal{K}^{\alpha}(H) = (H^{\alpha}, M^b(H)^{\alpha}, \circ, *)$ becomes a hypergroup which is called an orbital hypergroup of H by the action α .

Example 1 The orbital hypergroup $\mathcal{K}^{\alpha}(\mathbb{Z}_q(3)) = \{c_0, c_1\}$ is a *q*-deformation of $\mathcal{K}^{\alpha}(\mathbb{Z}_3)$. The structure equations are

$$\delta_{c_1} \circ \delta_{c_1} = \frac{q}{2} \delta_{c_0} + \left(1 - \frac{q}{2}\right) \delta_{c_1}.$$

Remark $\mathcal{K}^{\alpha}(\mathbb{Z}_q(3)) = \mathbb{Z}_{\frac{q}{2}}(2).$

Example 2 The orbital hypergroup $\mathcal{K}^{\alpha}(\mathbb{Z}_{(p,q)}(4)) = \{c_0, c_1, c_2\}$ is a q-deformation of $\mathcal{K}^{\alpha}(\mathbb{Z}_4)$.

The structure equations are

$$\begin{split} \delta_{c_1} \circ \delta_{c_1} &= p \delta_{c_0} + (1-p) \, \delta_{c_1}, \quad \delta_{c_1} \circ \delta_{c_2} = \delta_{c_2}, \\ \delta_{c_2} \circ \delta_{c_2} &= \frac{pq}{1+p} \delta_{c_0} + \frac{q}{1+p} \delta_{c_1} + (1-q) \delta_{c_2}. \end{split}$$

Remark $\mathcal{K}^{\alpha}(\mathbb{Z}_{(p,q)}(4)) = \mathbb{Z}_p(2) \vee \mathbb{Z}_q(2).$

5.2 Deformations of character hypergroups of semi-direct product hypergroups

Let $S = H \rtimes_{\alpha} G$ be a semi-direct product hypergroup defined by an action α of a finite abelian group G on a finite commutative hypergroup H (Refer to [5]). $\hat{S} = H \rtimes_{\alpha} G$ is the set of all equivalence classes of irreducible representations of S. For $(\pi, \mathcal{H}(\pi)) \in \hat{S}$, the character $ch(\pi)$ of π is defined by

$$ch(\pi)((h,g)) = \frac{1}{\dim \pi} \operatorname{tr}(\pi(h,g))$$

where $(h,g) \in H \rtimes_{\alpha} G$ and tr is the trace of $B(\mathcal{H}(\pi))$. Put $\mathcal{K}(\hat{S}) = \{ch(\pi) ; \pi \in \hat{S}\}.$

Proposition 5.1 ([5] and [7]) If the action α satisfies the regularity condition, then $\mathcal{K}(\widehat{H}\rtimes_{\alpha} G)$ becomes a commutative hypergroup by the product of functions on $S = H \rtimes_{\alpha} G$.

This hypergroup is called a character hypergroup of the semi-direct product hypergroup $S = H \rtimes_{\alpha} G$.

Example 3 The character hypergroup $\mathcal{K}(\widehat{S_q(3)})$ of $S_q(3) = \mathbb{Z}_q(3) \rtimes_{\alpha} \mathbb{Z}_2$ is a q-deformation of $\mathcal{K}(\widehat{S_3})$.

 $\widehat{S_q(3)} = \widehat{H \rtimes_{\alpha} G} = \{\chi_0 \odot \tau_0, \chi_0 \odot \tau_1, \pi\}, \text{ where } \pi \text{ is a two-dimensional irreducible representation of } S_q(3). \ \mathcal{K}(\widehat{S_q(3)}) = \{ch(\chi_0 \odot \tau_0), ch(\chi_0 \odot \tau_1), ch(\pi)\}. \text{ The character table is }$

	(h_0, e)	(h_1, e)	(h_2, e)	(h_0,g)	(h_1,g)	(h_2,g)
$\gamma_0 = ch(\chi_0 \odot \tau_0)$	1	1	1	1	1	1
$\gamma_1 = ch(\chi_0 \odot \tau_1)$	1	1	1	-1	-1	-1
$\gamma_2 = ch(\pi)$	1	$-\frac{q}{2}$	$-\frac{q}{2}$	0	0	0

and the structure equations of $\mathcal{K}(\widehat{S_q(3)})$ are

$$\gamma_1\gamma_1 = \gamma_0, \quad \gamma_2\gamma_2 = \frac{q}{4}\gamma_0 + \frac{q}{4}\gamma_1 + \left(1 - \frac{q}{2}\right)\gamma_2, \quad \gamma_1\gamma_2 = \gamma_2.$$

Example 4 The character hypergroup $\mathcal{K}(\widehat{D_{(p,q)}(4)})$ of $D_{(p,q)}(4) = \mathbb{Z}_{(p,q)}(4) \rtimes_{\alpha} \mathbb{Z}_2$ is a (p,q)-deformation of $\mathcal{K}(\widehat{D_4})$.

The structure equations of $\mathcal{K}(\widehat{D_{(p,q)}(4)}) = \{\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_4\}$ are

$$\begin{aligned} \gamma_1 \gamma_1 &= \gamma_0, \quad \gamma_1 \gamma_2 &= \gamma_3, \quad \gamma_1 \gamma_3 &= \gamma_2, \\ \gamma_2 \gamma_2 &= \gamma_3 \gamma_3 &= q \gamma_0 + (1-q) \gamma_2, \quad \gamma_2 \gamma_3 &= q \gamma_1 + (1-q) \gamma_3, \\ \gamma_4 \gamma_4 &= \frac{pq}{2(1+q)} \gamma_0 + \frac{pq}{2(1+q)} \gamma_1 + \frac{p}{2(1+q)} \gamma_2 + \frac{p}{2(1+q)} \gamma_3 + (1-p) \gamma_4, \\ \gamma_1 \gamma_4 &= \gamma_4, \quad \gamma_2 \gamma_4 &= \gamma_4, \quad \gamma_3 \gamma_4 &= \gamma_4. \end{aligned}$$

Example 5 The character hypergroup $\mathcal{K}(\widehat{Q_q(4)})$ of $Q_q(4) = \mathbb{Z}_{(1,q)}(4) \rtimes_{\alpha}^c \mathbb{Z}_2$ is a q-deformation of $\mathcal{K}(\widehat{D_4})$.

The structure equations of $\mathcal{K}(\widehat{Q_q(4)}) = \{\gamma_0, \gamma_1, \gamma_2, \gamma_3, \gamma_4\}$ are

$$\begin{split} \gamma_1 \gamma_1 &= \gamma_0, \quad \gamma_1 \gamma_2 = \gamma_3, \quad \gamma_1 \gamma_3 = \gamma_2, \\ \gamma_2 \gamma_2 &= \gamma_3 \gamma_3 = q \gamma_0 + (1-q) \gamma_2, \quad \gamma_2 \gamma_3 = q \gamma_1 + (1-q) \gamma_3, \\ \gamma_4 \gamma_4 &= \frac{q}{2(1+q)} \gamma_0 + \frac{q}{2(1+q)} \gamma_1 + \frac{1}{2(1+q)} \gamma_2 + \frac{1}{2(1+q)} \gamma_3, \\ \gamma_1 \gamma_4 &= \gamma_4, \quad \gamma_2 \gamma_4 = \gamma_4, \quad \gamma_3 \gamma_4 = \gamma_4. \end{split}$$

5.3 Deformations of generalized conjugacy class hypergroups

Let $S = H \rtimes_{\alpha} G$ be a semi-direct product hypergroup. Then there exists the canonical conditional expectation E from $M^b(S)$ onto the center $Z(M^b(S))$ of $M^b(S)$. Put

$$\mathcal{K}(H \rtimes_{\alpha} G) := \{ E(\delta_{(h,q)}) ; (h,g) \in H \rtimes_{\alpha} G \}$$

Proposition 5.2 ([6]) If the action α satisfies the regularity condition, then $\mathcal{K}(H \rtimes_{\alpha} G)$ becomes a commutative hypergroup with the convolution in the center $Z(M^b(S))$. Moreover $\widehat{\mathcal{K}}(H \rtimes_{\alpha} G) \cong \widehat{\mathcal{K}}(\widehat{H \rtimes_{\alpha} G})$ holds.

We call $\mathcal{K}(H \rtimes_{\alpha} G)$ a generalized conjugacy class hypergroup of $H \rtimes_{\alpha} G$.

Example 6 The generalized conjugacy class hypergroup $\mathcal{K}(S_q(3))$ of $S_q(3)$ is a q-deformation of $\mathcal{K}(S_3)$.

The structure equations of $\mathcal{K}(S_q(3)) = \{c_0, c_1, c_2\}$ are

$$\delta_{c_1} \circ \delta_{c_1} = \frac{q}{2} \delta_{c_0} + \left(1 - \frac{q}{2}\right) \delta_{c_1}, \quad \delta_{c_2} \circ \delta_{c_2} = \frac{q}{q+2} \delta_{c_0} + \frac{2}{q+2} \delta_{c_1}, \quad \delta_{c_1} \circ \delta_{c_2} = \delta_{c_2}.$$

Example 7 The generalized conjugacy class hypergroup $\mathcal{K}(D_{(p,q)}(4))$ of $D_{(p,q)}(4)$ is a (p,q)-deformation of $\mathcal{K}(D_4)$.

The structure equations of $\mathcal{K}(D_{(p,q)}(4)) = \{c_0, c_1, c_2, c_3, c_4\}$ are

$$\begin{split} \delta_{c_1} \circ \delta_{c_1} &= \delta_{c_4} \circ \delta_{c_4} = \frac{pq}{1+p} \delta_{c_0} + (1-q)\delta_{c_1} + \frac{q}{1+p}\delta_{c_2}, \\ \delta_{c_2} \circ \delta_{c_2} &= p\delta_{c_0} + (1-p)\delta_{c_2}, \quad \delta_{c_3} \circ \delta_{c_3} = \frac{p}{1+p}\delta_{c_0} + \frac{1}{1+p}\delta_{c_2}, \\ \delta_{c_1} \circ \delta_{c_2} &= \delta_{c_1}, \quad \delta_{c_1} \circ \delta_{c_3} = \delta_{c_4}, \quad \delta_{c_1} \circ \delta_{c_4} = q\delta_{c_3} + (1-q)\delta_{c_4}, \\ \delta_{c_2} \circ \delta_{c_4} &= \delta_{c_4}, \quad \delta_{c_2} \circ \delta_{c_3} = \delta_{c_3}, \quad \delta_{c_3} \circ \delta_{c_4} = \delta_{c_1}. \end{split}$$

Example 8 The generalized conjugacy class hypergroup $\mathcal{K}(Q_q(4))$ of $Q_q(4)$ is a q-deformation of $\mathcal{K}(Q_4)$.

The structure equations of $\mathcal{K}(Q_q(4)) = \{c_0, c_1, c_2, c_3, c_4\}$ are

$$\begin{split} \delta_{c_1} \circ \delta_{c_1} &= \delta_{c_4} \circ \delta_{c_4} = \frac{q}{2} \delta_{c_0} + (1-q) \delta_{c_1} + \frac{q}{2} \delta_{c_2}, \\ \delta_{c_2} \circ \delta_{c_2} &= \delta_{c_0}, \quad \delta_{c_3} \circ \delta_{c_3} = \frac{1}{2} \delta_{c_0} + \frac{1}{2} \delta_{c_2}, \\ \delta_{c_1} \circ \delta_{c_2} &= \delta_{c_1}, \quad \delta_{c_1} \circ \delta_{c_3} = \delta_{c_4}, \quad \delta_{c_1} \circ \delta_{c_4} = q \delta_{c_3} + (1-q) \delta_{c_4}, \\ \delta_{c_2} \circ \delta_{c_4} &= \delta_{c_4}, \quad \delta_{c_2} \circ \delta_{c_3} = \delta_{c_3}, \quad \delta_{c_3} \circ \delta_{c_4} = \delta_{c_1}. \end{split}$$

By the above structure equations, we have the following theorem.

Theorem There are deformations $S_q(3) = \mathbb{Z}_q(3) \rtimes_{\alpha} \mathbb{Z}_2$ of the symmetric group S_3 , $D_{(p,q)}(4) = \mathbb{Z}_{(p,q)}(4) \rtimes_{\alpha} \mathbb{Z}_2$ and $W_q(4) = (\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)) \rtimes_{\beta} \mathbb{Z}_2$ of the dihedral group D_4 and $Q_q(4) = \mathbb{Z}_{(1,q)}(4) \rtimes_{\alpha}^c \mathbb{Z}_2$ of the quaternion group Q_4 in the category of hypergroups. These deformations have the following properties.

(1) $\mathcal{K}(\widehat{S_q(3)}) = \mathbb{Z}_2 \vee \mathbb{Z}_{\frac{q}{2}}(2)$ and $\mathcal{K}(S_q(3)) = \mathbb{Z}_{\frac{q}{2}}(2) \vee \mathbb{Z}_2.$

(2) $\mathcal{K}(\widehat{D_{(p,q)}(4)})$ is a (q, p)-deformation of $\mathcal{K}(\widehat{D_4})$ and $\mathcal{K}(D_{(p,q)}(4))$ is a (p,q)-deformation of $\mathcal{K}(D_4)$. $\mathcal{K}(\widehat{Q_q(4)})$ is a q-deformation of $\mathcal{K}(\widehat{Q_4})$ and $\mathcal{K}(Q_q(4))$ is a q-deformation of $\mathcal{K}(Q_4)$. Moreover $\mathcal{K}(\widehat{D_{(1,q)}(4)}) \cong \mathcal{K}(\widehat{Q_q(4)})$ and $\mathcal{K}(D_{(1,q)}(4)) \cong \mathcal{K}(Q_q(4))$ although $D_{(1,q)}(4)$ is not isomorphic to $Q_q(4)$.

(3) $\mathcal{K}(\widetilde{W}_q(4))$ is not a hypergroup when $q \neq 1$.

Proof (1) We put $\mathbb{Z}_2 = \{b_0, b_1\}$ and $\mathbb{Z}_{\frac{q}{2}}(2) = \{c_0, c_1\}$, where $\delta_{b_1} \circ \delta_{b_1} = \delta_{b_0}$ and $\delta_{c_1} \circ \delta_{c_1} = \frac{q}{2}\delta_{c_0} + (1 - \frac{q}{2})\delta_{c_1}$ ($0 < q \leq 1$). The structure of $\mathcal{K}(\widehat{S_q(3)})$ in Example 3 is the same of the hypergroup join $\mathbb{Z}_2 \vee \mathbb{Z}_{\frac{q}{2}}(2)$. Hence $\mathcal{K}(\widehat{S_q(3)}) = \mathbb{Z}_2 \vee \mathbb{Z}_{\frac{q}{2}}(2)$. In a similar way we get $\mathcal{K}(S_q(3)) = \mathbb{Z}_{\frac{q}{2}}(2) \vee \mathbb{Z}_2$ as in Example 6.

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(2) The former properties follow directly from above examples 4, 7, 5 and 8. Both of $D_{(1,q)}(4)$ and $Q_q(4)$ are extension hypergroups of \mathbb{Z}_2 by $\mathbb{Z}_{(1,q)}(4)$. However $D_{(1,q)}(4)$ is of splitting type but $Q_q(4)$ is of non-splitting type. Hence $D_{(1,q)}(4)$ is not isomorphic to $Q_q(4)$.

(3) We put
$$\mathbb{Z}_q(\widehat{2}) \times \mathbb{Z}_q(2) = \{\chi_0, \chi_1, \chi_2, \chi_3\}$$
 and $\widehat{\mathbb{Z}}_2 = \{\tau_0, \tau_1\}$. Then

$$\widehat{W_q(4)} = \{\chi_0 \odot \tau_0, \chi_0 \odot \tau_1, \chi_3 \odot \tau_0, \chi_3 \odot \tau_1, \pi\},$$

where π is the two-dimensional irreducible representation of $W_q(4)$ given by

$$\pi = \operatorname{ind}_{\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)}^{W_q(4)} (\chi_1 \odot \tau_0).$$

Hence,

$$\mathcal{K}(\widehat{W_q(4)}) = \{ ch(\chi_0 \odot \tau_0), ch(\chi_0 \odot \tau_1), ch(\chi_3 \odot \tau_0), ch(\chi_3 \odot \tau_1), ch(\pi) \}$$

Assume that $\mathcal{K}(\widehat{W_q(4)})$ is a hypergroup for $q \neq 1$. Then

$$ch(\chi_3 \odot \tau_0)ch(\chi_3 \odot \tau_0) = a_0 ch(\chi_0 \odot \tau_0) + a_1 ch(\chi_0 \odot \tau_1) + a_2 ch(\chi_3 \odot \tau_0) + a_3 ch(\chi_3 \odot \tau_1) + a_4 ch(\pi)$$

where $\sum_{j=0}^4 a_j = 1$ and $a_j \ge 0$ $(j = 0, 1, 2, 3, 4)$. Since

$$ch(\chi_0 \odot \tau_1)(h_0, g) = -1, \ ch(\chi_3 \odot \tau_1)(h_0, g) = -1,$$

$$ch(\pi)(h_0,g) = 0$$
 and $ch(\chi_3 \odot \tau_0)ch(\chi_3 \odot \tau_0)(h_0,g) = 1$

where h_0 is the unit of $\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)$ and $\mathbb{Z}_2 = \{e, g\}, g^2 = e$, we see that

$$a_0 - a_1 + a_2 - a_3 = 1.$$

This implies that $a_1 = 0, a_3 = 0, a_4 = 0$. Hence, we get

$$ch(\chi_3 \odot \tau_0)ch(\chi_3 \odot \tau_0) = a_0ch(\chi_0 \odot \tau_0) + a_2ch(\chi_3 \odot \tau_0)$$

Restricting this equality to $\mathbb{Z}_q(2) \times \mathbb{Z}_q(2)$, we obtain

$$\chi_3 \chi_3 = a_0 \chi_0 + a_2 \chi_3.$$

This contradicts with the fact :

$$\chi_3\chi_3 = q^2\chi_0 + q(1-q)\chi_1 + q(1-q)\chi_2 + (1-q)^2\chi_3.$$

Hence, $\mathcal{K}(\widehat{W_q(4)})$ is not a hypergroup when $q \neq 1$.

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Addresses

Satoshi Kawakami : Nara University of Education Department of Mathematics Takabatake-cho Nara, 630-8528 Japan

e-mail : kawakami@nara-edu.ac.jp

Tatsuya Tsurii : Graduate School of Science of the Osaka Prefecture University 1-1 Gakuen-cho, Nakaku, Sakai Osaka, 599-8531 Japan e-mail : dw301003@edu.osakafu-u.ac.jp

Satoe Yamanaka : Nara University of Education Department of Mathematics Takabatake-cho Nara, 630-8528 Japan e-mail : s.yamanaka516@gmail.com